

Supplementary Material for “Progressive Label Propagation for Semi-Supervised Multi-Dimensional Classification”

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To facilitate understanding, Table 1 summarizes the notations used in Section 3 and Algorithm 1 further presents the pseudo code of the proposed PLAP approach.

Table 1: Summary of the notations used in our paper.

| Notation | Descriptions |
|-------------------------------|--|
| d | number of features in input space |
| q | number of class spaces (dimensions) in output space |
| K_j | number of class labels in the j -th class space ($1 \leq j \leq q$) |
| L | number of labeled MDC samples |
| U | number of unlabeled MDC samples |
| N | number of MDC samples, i.e., $N = L + U$ |
| \mathcal{X} | the d -dimensional input (feature) space, i.e., $\mathcal{X} = \mathbb{R}^d$ |
| C_j | the j -th class space where $C_j = \{c_1^j, c_2^j, \dots, c_{K_j}^j\}$ ($1 \leq j \leq q$) |
| c_a^j | the a -th class label in C_j ($1 \leq a \leq K_j$) |
| \mathcal{Y} | the output space where $\mathcal{Y} = C_1 \times C_2 \times \dots \times C_q$ |
| \mathcal{D}_l | the set of labeled MDC samples where $\mathcal{D}_l = \{(\mathbf{x}_i, \mathbf{y}_i) \mid 1 \leq i \leq L\}$ |
| \mathcal{D}_u | the set of unlabeled MDC samples where $\mathcal{D}_u = \{\mathbf{x}_i \mid L + 1 \leq i \leq L + U\}$ |
| \mathcal{D} | the set of MDC samples where $\mathcal{D} = \mathcal{D}_l \cup \mathcal{D}_u$ |
| \mathbf{x}_i | the i -th feature vector where $\mathbf{x}_i = [x_{i1}, x_{i2}, \dots, x_{id}]^\top \in \mathcal{X}$ |
| \mathbf{y}_i | the i -th class vector where $\mathbf{y}_i = [y_{i1}, y_{i2}, \dots, y_{iq}]^\top \in \mathcal{Y}$ |
| f | the SSMDC predictive model: $\mathcal{X} \mapsto \mathcal{Y}$ from $\mathcal{D} = \mathcal{D}_l \cup \mathcal{D}_u$ |
| \mathbf{W} | the affinity matrix defined based on the Gaussian function, i.e., $W_{ij} = e^{-\frac{\ \mathbf{x}_i - \mathbf{x}_j\ ^2}{2\sigma^2}}$ if $i \neq j$ and $W_{ii} = 0$ |
| σ | the bandwidth parameter of Gaussian function |
| \mathbf{S} | the propagation matrix where $\mathbf{S} = \mathbf{D}^{-\frac{1}{2}} \mathbf{W} \mathbf{D}^{-\frac{1}{2}}$ |
| \mathbf{D} | the diagonal matrix where $\mathbf{D} = \text{diag}(d_1, d_2, \dots, d_N)$ with $d_i = \sum_{j=1}^N W_{ij}$ |
| α | the hyper-parameter to be specified for balancing the importance of $\mathbf{S}\mathbf{F}(t)$ and \mathbf{Y} In Eq.(2) |
| \mathbf{Y} | the initial label matrix where Y_{ia} denotes the (i, a) -th item of \mathbf{Y} |
| $\mathbf{F}(t)$ | the propagated label matrix in the t -th round ($t \in \{1, 2, \dots\}$) and $\mathbf{F}(0) = \mathbf{Y}$ |
| $\phi_j(\cdot, \dots, \cdot)$ | the injective function from the Cartesian product $\{1, 2, \dots, K_1\} \times \{1, 2, \dots, K_2\} \times \dots \times \{1, 2, \dots, K_j\}$ to natural numbers $\{1, 2, \dots, K_1 \times K_2 \times \dots \times K_j\}$ |
| $\phi_j^{-1}(\cdot)$ | the inverse function of $\phi_j(\cdot, \dots, \cdot)$ |
| $\mathcal{N}(\mathbf{x}_i)$ | the k nearest neighbors of \mathbf{x}_i identified in labeled samples \mathcal{D}_l |
| n_{ia}^j | the number of samples with class label c_a^j w.r.t. C_j in $\mathcal{N}(\mathbf{x}_i)$ |
| CL_i^j | the condition for labeled sample \mathbf{x}_i to initialize \mathbf{Y} where $\text{CL}_i^j \triangleq (y_{i1} = c_{a_1}^1) \wedge \dots \wedge (y_{ij} = c_{a_j}^j)$ |
| CU_i^j | the condition for unlabeled sample \mathbf{x}_i to initialize \mathbf{Y} where $\text{CU}_i^j \triangleq (a_1 = \hat{a}_1) \wedge \dots \wedge (a_{j-1} = \hat{a}_{j-1})$ |

Algorithm 1 The PLAP approach

Input: The labeled MDC samples \mathcal{D}_l , unlabeled samples \mathcal{D}_u , the number of nearest neighbors k

Output: Predicted class vector $\hat{\mathbf{y}}_i$ for unlabeled sample $\mathbf{x}_i \in \mathcal{D}_u$

- 1: Construct the affinity matrix \mathbf{W} according to Eq.(1) and then calculate the propagation matrix \mathbf{S} based on \mathbf{W} ;
- 2: Set the value of label matrix \mathbf{Y} according to Eq.(3);
- 3: Iterate Eq.(2) with calculated \mathbf{S} and \mathbf{Y} until convergence;
- 4: Obtain the predicted class label \hat{y}_{i1} w.r.t. C_1 for unlabeled sample $\mathbf{x}_i \in \mathcal{D}_u$ according to Eq.(4);
- 5: Identify the k nearest neighbors of unlabeled sample $\mathbf{x}_i \in \mathcal{D}_u$ from labeled samples \mathcal{D}_l and store them in $\mathcal{N}(\mathbf{x}_i)$;
- 6: **while** $2 \leq j \leq q$ **do**
- 7: Update \mathbf{Y} according to Eq.(8) and Eq.(9);
- 8: Iterate Eq.(2) with \mathbf{S} and updated \mathbf{Y} until convergence;
- 9: Obtain the predicted class labels $\hat{y}_{i1}, \dots, \hat{y}_{ij}$ w.r.t. C_1, \dots, C_j for unlabeled sample $\mathbf{x}_i \in \mathcal{D}_u$ according to the generalized version for the j -th class space of Eq.(7);
- 10: $j \leftarrow j + 1$;
- 11: **end while**
- 12: **return** Predicted results $\{\hat{\mathbf{y}}_i \mid L + 1 \leq i \leq L + U\}$